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# A SOLUTION OF HADWIGER'S COVERING PROBLEM FOR ZONOIDS

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For a convex body  $M \subset \mathbb{R}^n$  by b(M) the least integer p is denoted, such that there are bodies  $M_1, \ldots, M_p$  each of which is homothetic to M with a positive ratio k < 1 and  $M_1 \cup \ldots \cup M_p \supset M$ . H. Martini has proved [7] that  $b(M) \leq 3 \cdot 2^{n-2}$  for every zonotope  $M \subset \mathbb{R}^n$ , which is not a parallelotope.

In the paper this Martini's result is extended to zonoids. In the proof some notions and facts of real functions theory are used (points of density, approximative continuity).

Let  $M \subset \mathbb{R}^n$  be a compact convex set. We denote by b(M) the least natural number p, such that there are sets  $M_1, \ldots, M_p$ , each of which is homothetic to M with a positive multiple k < 1 and  $M_1 \cup \ldots \cup M_p \supset M$ . It is clear that, if M is an n-dimensional parallelotope, then  $b(M) = 2^n$ . H. Hadwiger [1] has formulated a hypothesis, which asserts that if a convex set  $M \subset \mathbb{R}^n$  is not a parallelotope, then  $b(M) < 2^n$ . For n > 2 problem of Hadwiger is open up to now. An interesting partial result to this hard covering problem was obtained by M. Lassak [2]. In this paper we give a positive solution of Hadwiger's covering problem for a class of convex bodies, which are called zonoids.

**Definition.** A zonotope [3], [4] is a convex polytope, which is the vector sum of segments. A zonoid [5] is a limit (in the sense of the Hausdorff metric) of a convergent sequence of zonotopes.

In [5] another definition of zonoids is given. Namely, let  $\varphi(s)$ ,  $0 \le s \le \ell$ , be a vector-function of finite variation, such that the parameter s is the length on the curve  $x = \varphi(s)$ , i.e. the length of the arc with end points  $\varphi(0)$  and  $\varphi(s)$  is equal to s. We consider an integral (in Lebesque's sense)

(1) 
$$x(g) = \int_{0}^{\ell} g(s)\varphi'(s)\mathrm{d}s,$$

where g(s) is a measurable function, such that  $|g(s)| \le 1/2$  for every  $s \in [0, \ell]$ . Then the set of all points x(g) is a zonoid. Conversely, each zonoid may be represented in such a form. For other definitions of zonoids see [6], [4].

**Theorem.** For zonoids the conjecture of Hadwiger is true. More exactly, if a zonoid  $Z \subset \mathbb{R}^n$  is not a parallelotope, then  $b(Z) \leq 3 \cdot 2^{n-2}$ .

In Martini's paper [7] an analogous result is established for zonotopes. We shall obtain a proof of the theorem for zonoids with the help of a complicated limit process, which uses a notion of an approximate derivative [8].

First of all we recall that for every compact body M, Hadwiger's covering problem is equivalent to the illumination problem [9], [11], i.e. the minimal number of bodies, which are homothetic to M with a positive multiple k < 1 and cover M, is equal to the minimal number of directions, which illuminate the boundary of the body M.

Now we sketch a proof of Martini's result. Let M be an n-dimensional zonotope of  $\mathbb{R}^n$ . Then there are vectors  $e_1, \ldots, e_p$   $(p \ge n)$ , such that, up to a translation, M is the set of all points

$$x_1e_1 + \ldots + x_pe_p$$
  $(|x_i| \le 1/2 \text{ for all } i).$ 

We may suppose that  $e_i$  is not parallel to  $e_j$  for  $i \neq j$ , and that  $e_1, \ldots, e_n$  is a basis in  $\mathbb{R}^n$ . Then p > n, since M is not a parallelotope. Let us denote by  $M_1$  the set of all points  $x_1e_1+\ldots+x_ne_n+x_{n+1}e_{n+1}$  and by  $M_2$  the set of all points  $x_{n+2}e_{n+2}+\ldots+x_pe_p$  ( $|x_i| \leq 1/2$ ). Then  $M = M_1 + M_2$  and therefore  $b(M) \leq b(M_1)$  (by virtue of Lemma 1 below). Consequently, it is enough to prove that  $b(M_1) \leq 3 \cdot 2^{n-2}$ . Let

(2) 
$$\lambda_1 e_1 + \ldots + \lambda_n e_n + \lambda_{n+1} e_{n+1} = 0$$

be a nontrivial linear dependence. Then  $\lambda_{n+1} \neq 0$  and at least two of the numbers  $\lambda_1, \ldots, \lambda_n$  are not equal to 0 (since  $e_{n+1}$  is not parallel to  $e_i$  for any  $i = 1, \ldots, n$ ). We may suppose (replacing, if necessary,  $e_i$  by  $-e_i$ ), that all  $\lambda_i$  are nonnegative and

(3) 
$$\lambda_{n-1} > 0, \qquad \lambda_n > 0, \qquad \lambda_{n+1} > 0.$$

Each vertex q of  $M_1$  has a form

(4) 
$$q = \frac{1}{2}(\sigma_1 e_1 + \ldots + \sigma_n e_n + \sigma_{n+1} e_{n+1}), \text{ where } |\sigma_i| = 1 \text{ for all } i$$

(although not each of the points (4) is a vertex).

Let us fix a combination of signs  $\sigma_1 = \pm 1, \ldots, \sigma_{n-1} = \pm 1$ . There are, at most 8 vertices of  $M_1$  with this combination of sings (because, in order to get a vertex, it is sufficient to choose  $\sigma_{n-1} = \pm 1$ ,  $\sigma_n = \pm 1$ ,  $\sigma_{n+1} = \pm 1$ ). It is easy to see that all these 8 vertices are illuminated by the following three directions

$$a_1=-f+\varepsilon(e_n-e_{n-1}), \qquad a_2=-f+\varepsilon(e_{n+1}-e_n), \qquad a_3=-f+\varepsilon(e_{n-1}-e_{n+1}),$$

where  $f = (\sigma_1 e_1 + \ldots + \sigma_{n-2} e_{n-2})/2$  and  $\varepsilon > 0$  is small enough. Indeed, according to (2) and (3):

two vertices (4) with  $\sigma_{n-1} = 1$ ,  $\sigma_n = -1$  are illuminated by  $a_1$ ; two vertices (4) with  $\sigma_n = 1$ ,  $\sigma_{n+1} = -1$  are illuminated by  $a_2$ ; two vertices (4) with  $\sigma_{n+1} = 1$ ,  $\sigma_{n-1} = -1$  are illuminated by  $a_3$ ;

two vertices (4) with  $\sigma_{n-1} = \sigma_n = \sigma_{n+1}$  are illuminated by any  $a_i$ .

Thus, all vertices with a fixed combination of signs  $\sigma_1, \ldots, \sigma_{n-2}$  are illuminated by three directions. Since there are  $2^{n-2}$  combinations of signs  $\sigma_1 = \pm 1, \ldots, \sigma_{n-2} = \pm 1$ , then all the vertices of  $M_1$  may be illuminated by  $3 \cdot 2^{n-2}$  directions. Consequently, by [9],  $b(M_1) \leq 3 \cdot 2^{n-2}$ .

We now establish several lemmas, which will give us a way to prove the theorem in the general case.

**Lemma 1.** Let a compact convex body  $M \subset \mathbb{R}^n$  be a vector sum of two convex sets  $M_1, M_2$ . If  $M_1$  is n-dimensional, then  $b(M) \leq b(M_1)$ .

**Proof.** We put  $b(M_1) = h$ . Let  $a_1, \ldots, a_h$  be vectors in  $\mathbb{R}^n$ , whose directions illuminate the boundary bd  $M_1$  of the convex body  $M_1$ . Let c be an arbitrary boundary point of M. Then there are points  $c_1 \in M_1$ ,  $c_2 \in M_2$ , such that  $c = c_1 + c_2$ . It is clear that  $c_1$  is a boundary point of  $M_1$  (otherwise c could not be a boundary point of M). Let j be an index, such that the point  $c_1 \in \operatorname{bd} M_1$  is illuminated by the direction  $a_j$ , i.e. there is an interior point  $x_1 \in M_1$ , such that  $x_1 - c_1 = \lambda a_j$ ,  $\lambda > 0$ . We put  $x = x_1 + c_2$ . Then x is an interior point of M (since  $x_1 \in \operatorname{int} M_1$ ,  $c_2 \in M_2$ ). Further,

$$x-c=(x_1+c_2)-(c_1+c_2)=x_1-c_1=\lambda a_i$$

and therefore the point  $c \in \operatorname{bd} M$  is illuminated by the direction  $a_j$ . Thus each boundary point c of M is illuminated by a direction  $a_j$   $(j=1,\ldots,h)$ . Consequently, by [9],  $b(M) \leq h = b(M_1)$ .

The following lemma affirms that the function b(M), defined on the family of all convex sets in  $\mathbb{R}^n$ , possesses the upper semicontinuity property.

**Lemma 2.** If a sequence  $M_1, M_2, \ldots$  of compact convex bodies converges to a convex body M, then  $b(M) \ge \overline{\lim_{k \to \infty}} b(M_k)$ .

**Proof.** We put b(M) = h. Let  $a_1, \ldots, a_h$  be vectors in  $\mathbb{R}^n$ , such that their directions illuminate  $\operatorname{bd} M$ . Then there are compact sets  $\mathcal{D}_1, \ldots, \mathcal{D}_h$ , such that  $\mathcal{D}_1 \cup \ldots \cup \mathcal{D}_h = \operatorname{bd} M$  and every point  $x \in \mathcal{D}_j$  is illuminated by the direction  $a_j$ . Let us denote by  $T_j^\lambda$  the translation  $x \mapsto x + \lambda a_j$  in  $\mathbb{R}^n$ . We fix a number  $\lambda > 0$ , such that  $T_j^\lambda(\mathcal{D}_j) \subset \operatorname{int} M$  for every  $j = 1, \ldots, h$ . Let us denote by V an open set in  $\mathbb{R}^n$ , such that  $\operatorname{cl} V \subset \operatorname{int} M$  and  $V \supset T_1^\lambda(\mathcal{D}_1) \cup \ldots \cup T_h^\lambda(\mathcal{D}_h)$ . We choose for every  $j = 1, \ldots, h$  an open set  $W_j \subset \mathbb{R}^n$ , such that  $W_j \supset \mathcal{D}_j$  and  $T_j^\lambda(W_j) \subset V$ . Then  $W_1 \cup \ldots \cup W_h \supset \operatorname{bd} M$ .

Let  $\delta > 0$  be such that if  $d(M,N) < \delta$  then  $\operatorname{cl} V \subset \operatorname{int} N$  and  $\operatorname{bd} N \subset W_1 \cup \ldots \cup W_h$  (where d is the Hausdorff metric). We are going to show that if  $d(M,N) < \delta$ , then  $b(N) \leq b(M)$ . Indeed, let  $x \in \operatorname{bd} N$ . Then there is j, such that  $x \in W_j$ . Consequently,

$$x+\lambda a_j=T_j^\lambda(x)\in T_j^\lambda(W_j)\subset V\subset\operatorname{cl} V\subset\operatorname{int} N,$$

i.e. the point x is illuminated by the direction  $a_j$ . Thus, each boundary point x of the body N is illuminated by a direction  $a_j$   $(j=1,\ldots,h)$ , i.e.  $b(N) \le h = b(M)$ .

Let now  $M_1, \ldots, M_2, \ldots$  be a sequence of compact convex bodies in  $\mathbb{R}^n$ , which converges to a convex body M. There is an integer  $k_0$ , such that  $d(M, M_k) < \delta$  for every  $k > k_0$ . Consequently,  $b(M_k) \le b(M)$  for all  $k > k_0$  and therefore  $\lim_{k \to \infty} b(M_k) \le b(M)$ .

The following examples illustrate the statement of Lemma 2.

**Example 1.** Let us introduce Cartesian coordinates  $x_1, ..., x_n$  in  $\mathbb{R}^n$  and denote by  $M_k$  the parallelotope, which is described by the inequalities

$$|x_1| \le 1$$
,  $|x_2| \le 1$ , ...,  $|x_{n-1}| \le 1$ ,  $|x_n| \le 1/k$ .

The parallelotopes  $M_k$  become more and more "thin" when  $k\to\infty$ , and the sequence  $M_1, M_2, \ldots$  converges to the (n-1)-dimensional parallelotope M defined by the relations

$$|x_1| \le 1$$
,  $|x_2| \le 1$ , ...,  $|x_{n-1}| \le 1$ ,  $x_n = 0$ .

Thus  $b(M_k) = 2^n$ ,  $b(M) = 2^{n-1}$ , i.e. the inequality of Lemma 2 is not true in this case. This means that the requirement in Lemma 2 that M be a body is essential.

**Example 2.** Let  $M \subset \mathbb{R}^n$  be an n-dimensional parallelotope and  $M_k$  its 1/k-neighborhood,  $k=1,2,\ldots$  Then  $\lim_{k\to\infty}M_k=M$  and  $b(M_k)=n+1,\ b(M)=2^n$ . It means that the inequality  $b(M)\leq \varliminf_{k\to\infty}b(M_k)$  is not true in this case, i.e. unfortu-

nately, there is no corresponding property lower semicontinuity.

By the way lower semicontinuity would allow to obtain our theorem by a direct limit process (from Martini's result). In this connection we use a suitable indirect method.

Let  $Z \subset \mathbb{R}^n$  be a zonoid,  $\varphi(s)$ ,  $0 \le s \le \ell$ , its determining vector-function (cf. (1)) and  $s_1, \ldots, s_k$  points of segment  $[0, \ell]$ , such that at each of these points the derivative  $\varphi'(s)$  exists and is approximately continuous. Then the vector sum of k segments, respectively parallel to the vectors  $\varphi'(s_1), \ldots, \varphi'(s_k)$ , is called a *tangential zonotope* of zonoid Z.

**Lemma 3.** Let  $Z \subset \mathbb{R}^n$  be a zonoid and M one of its tangential zonotopes. If M is a body, then  $b(Z) \leq b(M)$ .

**Proof.** Let  $\varphi(s)$ ,  $0 \le s \le \ell$ , be a determining vector-function of Z (cf. (1)). Then there are points  $s_1, \ldots, s_k \in [0, \ell]$ , at which  $\varphi'(s)$  exists and is approximately continuous, and vectors  $e_1, \ldots, e_k$ , which are correspondingly parallel to  $\varphi'(s_1), \ldots, \varphi'(s_k)$ , such that M is the set of all points  $\mu_1 e_1 + \ldots + \mu_k e_k$ , where  $|\mu_i| \le 1/2$  for all i. We have  $\varphi'(s_i) = (1/\lambda_i) \cdot e_i$  where  $\lambda_i$  is the length of the vector  $e_i$ ,  $i = 1, \ldots, k$ .

Let b(M) = h and  $a_1, \ldots, a_h$  be vectors, such that their directions illuminate the boundary of the convex body M. Now let us construct for M the sets  $\mathcal{D}_j$ , V,  $W_j$  and the numbers  $\lambda$ ,  $\delta$  in the same way as in the proof of Lemma 2.

Since  $\varphi'(s)$  is approximately continuous at the point  $s_i$ , there is a set  $P_i \subset [0,\ell]$ , such that  $s_i$  is a point of density of the set  $P_i$  and at each point  $s \in P_i$  the derivative  $\varphi'(s)$  exists and satisfies the inequality  $|\varphi'(s) - \varphi'(s_i)| < \delta \cdot (\lambda_1 + \ldots + \lambda_k)^{-1}$ . We may suppose that each two of the sets  $P_1, \ldots, P_k$  are disjoint. Finally (passing to subsets if necessary), we may suppose that  $\operatorname{mes} P_i = q\lambda_i$ ,  $i = 1, \ldots, k$ , where q is a positive number.

We put  $P = P_1 \cup ... \cup P_k$ ,  $Q = [0, \ell] \setminus P$ . Let us denote by  $Z_1$ ,  $Z_2$  the sets of all points

$$z_1(g) = \int\limits_P g(s)\varphi'(s)\mathrm{d}s \qquad z_2(g) = \int\limits_Q g(s)\varphi'(s)\mathrm{d}s$$

respectively, where g(s) is a measurable function which satisfies the condition  $|g(s)| \le 1/2$  for all  $s \in [0, \ell]$ . Then

$$z_1(g) + z_2(g) = \int_P g(s)\varphi'(s)ds + \int_Q g(s)\varphi'(s)ds = \int_0^\ell g(s)\varphi'(s)ds,$$

and therefore  $Z = Z_1 + Z_2$ . We are now going to prove that  $Z_1$  is a convex body and  $b(Z_1) \le h$ .

On this purpose we put

$$x(g) = \int_{P_1} g(s)\varphi'(s_1)ds + \ldots + \int_{P_k} g(s)\varphi'(s_k)ds.$$

Then

$$x(g) = \varphi'(s_1) \int_{P_1} g(s) ds + \ldots + \varphi'(s_k) \int_{P_k} g(s) ds =$$

$$= \frac{1}{\lambda_1} e_1 \int_{P_1} g(s) ds + \ldots + \frac{1}{\lambda_k} e_k \int_{P_k} g(s) ds = \nu_1 e_1 + \ldots + \nu_k e_k,$$

where

$$|
u_i| = rac{1}{\lambda_i} \left| \int\limits_{P_i} g(s) \mathrm{d}s \right| \leq rac{1}{\lambda_i} \cdot rac{1}{2} \mathrm{mes} \, P_i = rac{1}{\lambda_i} \cdot rac{1}{2} q \lambda_i = rac{1}{2} q.$$

It follows from this that the set  $M^*$  of all points x(g) is a zonotope, which is homothetic to M with the multiple q.

Now we have

$$|z_{1}(g) - x(g)| = \left| \sum_{i} \left( \int_{P_{i}} g(s)\varphi'(s) ds - \int_{P_{i}} g(s)\varphi'(s_{i}) ds \right) \right| \le$$

$$\le \sum_{i} \int_{P_{i}} |g(s)| \cdot |\varphi'(s) - \varphi'(s_{i})| ds \le \sum_{i} \frac{1}{2} \cdot \frac{\delta}{\lambda_{1} + \ldots + \lambda_{k}} \operatorname{mes} P_{i} =$$

$$= \sum_{i} \frac{1}{2} \cdot \frac{\delta}{\lambda_{1} + \ldots + \lambda_{k}} \cdot q\lambda_{i} = \frac{1}{2} q\delta < q\delta.$$

Thus in the  $q\delta$ -neighborhood of each point  $z_1(g) \in Z_1$  there is a point  $x(g) \in M^*$  (namely, the point x(g) with the same function g(s)). Conversely, in the  $q\delta$ -neighborhood of each point  $x(g) \in M^*$  there is a point  $z_1(g) \in Z_1$ . Consequently,  $d(Z_1, M^*) < q\delta$ .

Let  $\gamma$  be a homothety with the multiple  $\frac{1}{q}$ , such that  $\gamma(M^*) = M$ . Then

$$d(\gamma(Z_1), M) = d(\gamma(Z_1), \gamma(M^*)) < \frac{1}{q} \cdot q\delta = \delta.$$

This means, in view of the choice of  $\delta$ , that  $\gamma(Z_1) \supset V$ , i.e.  $\gamma(Z_1)$  is a convex body, and  $b(\gamma(Z_1)) \leq h$ . It follows from this that  $b(Z_1) = b(\gamma(Z_1)) \leq h$ , which proves the Lemma.

**Lemma 4.** Each zonoid  $Z \subset \mathbb{R}^n$  may be represented as a limit of a convergent sequence of its tangential zonotopes.

**Proof.** Let  $\varphi(s)$ ,  $0 \le s \le \ell$ , be a determining vector-function of Z. We choose an arbitrary positive number  $\varepsilon$  and construct an  $\varepsilon$ -net  $\{e_1, \ldots, e_p\}$  on the unit sphere  $S_i^{n-1} \subset \mathbb{R}^n$ . Let  $E_i$   $(i=1,\ldots,p)$  be the set of all points  $s \in [0,\ell]$ , at which  $\varphi'(s)$  exists and satisfies the condition  $|\varphi'(s) - e_i| < \varepsilon$ . Almost all points of the segment  $[0,\ell]$  belong to  $E_1 \cup \ldots \cup E_p$ . We now put

$$F_1 = E_1; \quad F_i = E_i \setminus (E_1 \cup \ldots \cup E_{i-1}), \qquad i = 2, \ldots, p.$$

Then each two of the sets  $F_1, \ldots, F_p$  are disjoint, and almost all points of  $[0, \ell]$  belong to  $F_1 \cup \ldots \cup F_p$ . We shall suppose that all sets  $F_1, \ldots, F_p$  are nonvoid (void sets may be omitted).

For each  $i=1,\ldots,p$  we fix a point  $s_i \in F_i$  and put

$$z(g) = \sum_{i} \int_{F_i} g(s)\varphi'(s)ds, \quad x(g) = \sum_{i} \int_{F_i} g(s)\varphi'(s_i)ds; \quad |g(s)| \le \frac{1}{2}.$$

Then the set of all points z(g) is the given zonoid Z, and the set of all points x(g) is a zonotope  $M = I_1 + \ldots + I_p$ , where  $I_i$  is a segment which is parallel to  $\varphi'(s_i)$  and has a length  $|I_i| = \text{mes } F_i$ . We have

$$\begin{aligned} |z(g) - x(g)| &= \\ \left| \sum_{i} \left( \int_{F_{i}} g(s) \varphi'(s) \mathrm{d}s - \int_{F_{i}} g(s) \varphi'(s_{i}) \mathrm{d}s \right) \right| &\leq \sum_{i} \int_{F_{i}} |g(s)| \cdot |\varphi'(s) - \varphi'(s_{i})| \mathrm{d}s \leq \\ \sum_{i} \int_{F_{i}} |g(s)| \cdot \left( |\varphi'(s) - e_{i}| + |e_{i} - \varphi'(s_{i})| \right) \mathrm{d}s \leq \sum_{i} \int_{F_{i}} \frac{1}{2} \cdot 2\varepsilon \mathrm{d}s = \int_{0}^{\ell} \varepsilon \mathrm{d}s = \varepsilon \ell. \end{aligned}$$

This means that  $d(Z, M) \le \varepsilon \ell$ . This establishes the Lemma (since  $\varepsilon > 0$  is arbitrary small).

**Lemma 5.** If a zonoid Z is a limit of a convergent sequence  $M_1, M_2, \ldots$  of its tangential zonotopes, then  $b(Z) = \lim_{k \to \infty} b(M_k)$ .

It follows obviously from Lemmas 2 and 3.

Now the proof of the theorem follows immediately from the Lemmas 4, 5 and Martini's result [6].

Let us make some remarks which are connected with our main theorem. First of all, we give an extension of the notions of a zonotope.

We shall say a convex body is an *unbounded zonotope* if it is a vector sum of onedimensional convex sets, at least one of which is unbounded. An *unbounded zonoid*  is a convex set, which is a limit (in Hausdorff's sense) of a consequence  $M_1, M_2, \ldots$  of unbounded zonotopes.

Let us recall, that the *characteristic cone* of an unbounded convex set M with a vertex  $x_0 \in \text{int } M$  is the union of all rays with the initial points  $x_0$ , which are contained in M. The characteristic cone of M is determined up to translation. Let us also recall, that a *nearly conic* convex set is an unbounded convex set which is contained in a r-neighborhood of its characteristic cone for some positive number r. It is clear that each unbounded zonotope (and consequently, each unbounded zonoid) is a nearly conic set. For every nearly conic convex body M, Hadwiger's problem is equivalent to the illumination problem [10], [11].

Let M be a nearly conic convex body, K its characteristic cone, L a direct summand for the plane aff K and  $\pi: \mathbb{R}^n \to L$  the projection along aff K. Then the convex set  $N = \pi(M) \subset L$  is bounded, and we have the equality  $b(M) = b(\operatorname{cl} N)$  [10], [11]. The set  $\operatorname{cl} N$  is determined up to an affine transformation. We shall say that  $\operatorname{cl} N$  is a *limit projection* of the nearly conic convex body M. It is easy to prove that a limit projection of an unbounded zonotope is a bounded zonotope, and hence a limit projection of an unbounded zonoid is a bounded zonoid. From our main theorem we now obtain the following result:

Let Z be an unbounded zonoid and  $\operatorname{cl} N$  its limit projection. We put  $p = \dim \operatorname{cl} N$ . If  $\operatorname{cl} N$  is a parallelotope then  $b(Z) = 2^p$ , and if  $\operatorname{cl} N$  is not a parallelotope then  $b(Z) \le 3 \cdot 2^{p-2}$ .

Let us note that a generalization of the integral definition of zonoids (cf. (1)) leads us to a *larger* class of unbounded convex sets, than unbounded zonoids. Namely, let K be an unbounded curve with a vector equation  $x = \varphi(s)$ ,  $s \in \mathbb{R}$ , where the function  $\varphi(s)$  has a finite variation on each segment  $[a,b] \subset \mathbb{R}$  and s is a length (with an appropriate sign). Let us consider all the points

(5) 
$$x(g) = \int_{-\infty}^{\infty} g(s)\varphi'(s)\mathrm{d}s,$$

where g(s) is a measurable function, such that  $|g(s)| \le 1/2$  for all  $s \in \mathbb{R}$  and the integral (5) is convergent. Then the set of all points x(g) is an unbounded convex set, and the class of all such sets is larger than the class of all unbounded zonoids.

For example, let K be a parabola in a plane. Then the set Z of all the points (5) is the convex hull of this parabola, i.e. Z is not nearly conic.

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